# The cross ratio and its applications 

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## Plan

(1) Cross ratio

- Cross ratio in projective geometry
- Cross ratio in Möbius geometry
- Clifford cross ratio
(2) Van der Pauw method
- Resistivity measurements by the van der Pauw method
- Derivation of the van der Pauw formula
(3) Conformal mappings
- Complex potential
- Riemann mapping theorem
- Modification of the van der Pauw method

4 Discrete integrable submanifolds

- The Sym-Tafel formula
- Special classes of discrete immersions

Cross ratio in projective geometry Cross ratio in Möbius geometry Clifford cross ratio

## Cross ratio in projective geometry

known also as anharmonic ratio.
$s$ - natural parameter along a line. Cross ratio:

$$
\left(s_{1}, s_{2} ; s_{3}, s_{4}\right):=\frac{\left(s_{3}-s_{1}\right)\left(s_{4}-s_{2}\right)}{\left(s_{3}-s_{2}\right)\left(s_{4}-s_{1}\right)} \equiv \frac{\frac{s_{3}-s_{1}}{s_{3}-s_{2}}}{\frac{s_{4}-s_{1}}{s_{4}-s_{2}}}
$$

$\alpha$ - angle for lines in the corresponding pencil


Theorem: $\left(s_{1}, s_{2} ; s_{3}, s_{4}\right)=\left(\alpha_{1}, \alpha_{2} ; \alpha_{3}, \alpha_{4}\right)$

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\left(\alpha_{1}, \alpha_{2} ; \alpha_{3}, \alpha_{4}\right):=\frac{\sin \left(\alpha_{3}-\alpha_{1}\right) \sin \left(\alpha_{4}-\alpha_{2}\right)}{\sin \left(\alpha_{3}-\alpha_{2}\right) \sin \left(\alpha_{4}-\alpha_{1}\right)}
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## Projective invariance of the cross ratio

The idea of the proof is simple. Areas of triangles are computed in two ways:

$$
P_{j k}=\frac{1}{2}\left(s_{k}-s_{j}\right) h=\frac{1}{2} r_{j} r_{k} \sin \left(\alpha_{k}-\alpha_{j}\right)
$$

Corollary: Cross ratio - invariant of projective transformations.

## Cross ratio in Möbius geometry.

Möbius transformations: fractional linear transformations in $\mathbb{C}$.

$$
\left(z_{1}, z_{2} ; z_{3}, z_{4}\right):=\frac{\left(z_{3}-z_{1}\right)\left(z_{4}-z_{2}\right)}{\left(z_{3}-z_{2}\right)\left(z_{4}-z_{1}\right)}
$$

Cross ratio is invariant with respect to Möbius transformations:


- translations:
- rotations:
- dilations:
- reflection:
- inversion:

[Reflection and inversion change sign of the cross ratio.].]


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Cross ratio is invariant with respect to Möbius transformations:

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w(z)=\frac{a z+b}{c z+d}, \quad a d-b c \neq 0
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$$

- translations:

$$
w=z+a
$$

- rotations:

$$
w=e^{i \alpha} z, \quad \alpha \in \mathbb{R}
$$

- dilations: $\quad w=\lambda z, \quad \lambda \in \mathbb{R}$,
- reflection: $w=\bar{z}$,
- inversion: $w=\bar{z}^{-1}$
[Reflection and inversion change sign of the cross ratio.]


## Cross ratio in Möbius geometry

Automorphisms of the upper half-plane

Möbius transformations transform circles into circles (a straight line is considered as a degenerated circle, a circle containing $z=\infty$ ).

For $a, b, c, d \in \mathbb{R}$ Möbius transformation is an automorphism of the upper half-plane (preserving also geodesic lines). Indeed:

$$
\operatorname{Im}\left(\frac{a z+b}{c z+d}\right) \equiv \frac{a d-b c}{|c z+d|} \operatorname{Im} z
$$

## Cross ratio identities

There are $4!=24$ possible cross ratios of 4 points. Following identities can be directly verified:

$$
\begin{aligned}
& \left(x_{j}, x_{k} ; x_{m}, x_{n}\right)=\left(x_{m}, x_{n} ; x_{j}, x_{k}\right)=\left(x_{j}, x_{k} ; x_{n}, x_{m}\right)^{-1} \\
& \left(x_{j}, x_{k} ; x_{m}, x_{n}\right)+\left(x_{j}, x_{m} ; x_{k}, x_{n}\right)=1
\end{aligned}
$$

There are at most 6 different values:

$$
\begin{aligned}
& \left(z_{1}, z_{2} ; z_{3}, z_{4}\right) \equiv \lambda \\
& \left(z_{1}, z_{2} ; z_{4}, z_{3}\right)=\lambda^{-1} \\
& \left(z_{1}, z_{3} ; z_{4}, z_{2}\right)=(1-\lambda)^{-1} \\
& \left(z_{1}, z_{3} ; z_{2}, z_{4}\right)=1-\lambda, \\
& \left(z_{1}, z_{4} ; z_{2}, z_{3}\right)=1-\lambda^{-1} \\
& \left(z_{1}, z_{4} ; z_{3}, z_{2}\right)=\left(1-\lambda^{-1}\right)^{-1}
\end{aligned}
$$

## Clifford algebra $\mathcal{C}(V)$

## generated by a vector space $V$ equipped with a quadratic form $\langle\cdot \mid \cdot\rangle$

Clifford product satisfies: $\quad \boldsymbol{v} \boldsymbol{w}+\boldsymbol{w} \boldsymbol{v}=2\langle\boldsymbol{v} \mid \boldsymbol{w}\rangle \mathbf{1}, \quad(\boldsymbol{v}, \boldsymbol{w} \in V)$.

$$
\boldsymbol{v} \boldsymbol{w}=\langle\boldsymbol{v} \mid \boldsymbol{w}\rangle+\boldsymbol{v} \wedge \boldsymbol{w}
$$

The algebra $\mathcal{C}(V)$ ("Clifford numbers") is spanned by:
1 scalars
$\mathbf{e}_{k} \quad$ vectors $\quad \mathbf{e}_{k}^{2}= \pm 1, \quad \mathbf{e}_{j} \mathbf{e}_{k}=-\mathbf{e}_{k} \mathbf{e}_{j} \quad(k \neq j)$
$\mathbf{e}_{j} \mathbf{e}_{k}(\mathrm{j}<\mathrm{k}) \quad$ bi-vectors
$\mathbf{e}_{k_{1}} \ldots \mathbf{e}_{k_{r}}\left(k_{1}<k_{2}<\ldots<k_{r}\right)$ multi-vectors
$\mathbf{e}_{1} \mathbf{e}_{2} \ldots \mathbf{e}_{n} \quad$ volume element $n=p+q$
$\operatorname{dim} C I_{p, q}=2^{p+q}, \quad \mathcal{C}_{p, q} \equiv \mathcal{C}\left(\mathbb{R}^{p, q}\right)$.

Cross ratio

Cross ratio in projective geometry Cross ratio in Möbius geometry Clifford cross ratio

## Conformal transformations in $\mathbb{R}^{n}$ in terms of Clifford numbers

For $N \geqslant 3$ all conformal transformations are generated by

- Euclidean motions (translations, reflections, rotations)
- Dilations, inversions:

Translation
Reflection $\quad \boldsymbol{x}^{\prime}=-\boldsymbol{n x} \boldsymbol{n}^{-1} \quad$ [boldface: Clifford vectors]
Dilation


Inversion
Rotation (by Cartan's theorem) is a composition of reflections:
$x^{\prime}=n_{k} \ldots n_{\uparrow} \times n_{1}^{-1} \ldots n_{k}^{-1}$
The case $N=2$ : any holomorphic bijective function ispronformal.

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Translation $\quad \boldsymbol{x}^{\prime}=\boldsymbol{x}+\boldsymbol{c}$
Reflection $\quad \boldsymbol{x}^{\prime}=-\boldsymbol{n} \boldsymbol{x} \boldsymbol{n}^{-1} \quad$ [boldface: Clifford vectors]
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$$
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$$

The case $N=2$ : any holomorphic bijective function is conformal.

## Lipschitz group and Spin group

Lipschitz group (Clifford group) $\Gamma(V)$ is the multiplicative group (with respect to the Clifford product) generated by vectors:
$\boldsymbol{v}_{\mathbf{1}} \boldsymbol{v}_{\mathbf{2}} \ldots \boldsymbol{v}_{\boldsymbol{M}} \in \Gamma(V)$.
$\Gamma_{0}(V)$ is generated by even number of vectors.
$\operatorname{Pin}(V)$ subgroup generated by unit vectors
$\operatorname{Spin}(V)$ subgroup generated by even number of unit vectors.

$$
\begin{aligned}
& \operatorname{Spin}(V) \subset \operatorname{Pin}(V) \subset \Gamma(V) \subset \mathcal{C}(V) \\
& V \subset \operatorname{Pin}(V), \quad \Gamma_{0}(V) \subset \Gamma(V)
\end{aligned}
$$

$\operatorname{Pin}(V)$ and $\operatorname{Spin}(V)$ are double covering of $\mathrm{O}(V)$ and $\mathrm{SO}(V)$, respectively.

## The Clifford cross ratio

J. Cieśliński, The cross ratio and Clifford algebras, Adv. Appl. Clifford Alg. 7 (1997) 133.

For $X_{k} \in \mathbb{R}^{n} \subset \mathcal{C}\left(\mathbb{R}^{n}\right)$ we define:
$Q\left(X_{1}, X_{2}, X_{3}, X_{4}\right):=\left(X_{1}-X_{2}\right)\left(X_{2}-X_{3}\right)^{-1}\left(X_{3}-X_{4}\right)\left(X_{4}-X_{1}\right)^{-1}$.
In general, $Q\left(X_{1}, X_{2}, X_{3}, X_{4}\right) \in \Gamma_{0}\left(\mathbb{R}^{n}\right)$.
For $X_{k} \in \mathbb{R}^{p, q}$ the definition is not well defined if $X_{2}-X_{3}$ or $X_{4}-X_{1}$ are isotropic (null, non-invertible).

Droposition. $Q\left(X_{1}, X_{2}, X_{3}, X_{4}\right)$ is real (i.e., proportional to 1) if and only if $X_{1}, X_{2}, X_{3}, X_{4}$ lie on a circle or are co-linear.

Therefore the Clifford cross-ratio can be used to characterize discrete analogues of curvature nets, isothermic surfaces etc.

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Therefore the Clifford cross-ratio can be used to characterize discrete analogues of curvature nets, isothermic surfaces etc.

## Conformal covariance of the Clifford cross ratio

$$
\begin{array}{ll}
\boldsymbol{x} \rightarrow \boldsymbol{x}+\boldsymbol{c} & Q \rightarrow Q \\
\boldsymbol{x} \rightarrow \lambda \boldsymbol{x} & Q \rightarrow Q \\
\boldsymbol{x} \rightarrow-\boldsymbol{n} \boldsymbol{x} \boldsymbol{n}^{-1} & Q \rightarrow \boldsymbol{n} Q \boldsymbol{n}^{-1} \\
\boldsymbol{x} \rightarrow \boldsymbol{x}^{-1} & Q \rightarrow X_{1} Q X_{1}^{-1} \\
\boldsymbol{x} \rightarrow \boldsymbol{A} A^{-1} & Q \rightarrow A Q A^{-1}
\end{array}
$$

Corollary: Eigenvalues of the Clifford cross ratio are invariant under all conformal transformations.

## Cross ratio. Ordering conventions.

$$
\begin{gathered}
\left(x_{1}, x_{2} ; x_{3}, x_{4}\right) \equiv\left(x_{1}-x_{3}\right)\left(x_{3}-x_{2}\right)^{-1}\left(x_{2}-x_{4}\right)\left(x_{4}-x_{1}\right)^{-1} \\
Q\left(x_{1}, x_{2}, x_{3}, x_{4}\right)=\left(x_{1}-x_{2}\right)\left(x_{2}-x_{3}\right)^{-1}\left(x_{3}-x_{4}\right)\left(x_{4}-x_{1}\right)^{-1} \\
Q\left(x_{1}, x_{2}, x_{3}, x_{4}\right)=\left(x_{1}, x_{3} ; x_{2}, x_{4}\right)
\end{gathered}
$$

We proceed to presenting two different applications of the cross ratio: in electrostatics (van der Pauw method) and, then, in difference geometry (circular nets, isothermic nets).

## Assumptions of the van der Pauw method

Van der Pauw method (1958) is a standard method to measure resistivity of flat thin conductors.

- Flat, very thin, conducting sample
- Homogeneous, isotropic
- Arbitraty shape without holes (i.e., simply connected)
- Four point contacts on the circumference: A, B, C, D.

Method easily accessible for undergraduate students (provided that the van der Pauw formula is taken for granted).

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## The van der Pauw method. Typical samples.



## Measurements, notation, the van der Pauw formula

Two measurements:

- Current $J_{A B}$, voltage $U_{C D}=\Phi_{D}-\Phi_{C}$,
- Current $J_{B C}$, voltage $U_{D A}=\Phi_{A}-\Phi_{D}$,



## Van der Pauw formula ( $\sigma$ is to be determined):


$\sigma$ conductivity, p resistivity $\sigma=\frac{1}{\rho}$,
$d$ thickness of the sample

## Measurements, notation, the van der Pauw formula

Two measurements:

- Current $J_{A B}$, voltage $U_{C D}=\Phi_{D}-\Phi_{C}, \quad R_{A B, C D}=\frac{U_{C D}}{J_{A B}}$,
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Van der Pauw formula ( $\sigma$ is to be determined):

$$
e^{-\pi d \sigma R_{A B, C D}}+e^{-\pi d \sigma R_{B C, D A}}=1
$$

$\sigma$ conductivity, $\rho$ resistivity, $\sigma=\frac{1}{\rho}$,
d thickness of the sample

## Main idea of van der Pauw

- Computations are easy for (infinite) half-plane [intuitive physics].
- Exact positions of $A, B, C, D$ are not needed, their order is sufficient.
- The result does not depend on the shape of the sample (if simply connected) [proof: advanced mathematics].


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## Potential distribution on the conducting plane

(thin, homogeneous, isotropic: current enters at $z=A$ and flows out at $z=B$ ).

- Ohm's law: $\vec{j}=-\sigma \operatorname{grad} \Phi, \quad \Phi$ potential.
- Current $J$ entering at $z=A$ flows symmetrically to $\infty$.
- Conservation of electric charge: $2 \pi r d j=J, r=|z-A|$.
- $\frac{\partial \Phi}{\partial r}=-\rho j \Rightarrow \Phi_{1}(z)=-\frac{J \rho}{2 \pi d} \ln |z-A|$.
- For $J$ flowing out at $z=B, \quad \Phi_{2}(z)=\frac{J \rho}{2 \pi d} \ln |z-B|$.
- Finally, $\Phi(z)=\Phi_{1}(z)+\Phi_{2}(z)=\frac{J \rho}{2 \pi d} \ln \left|\frac{z-B}{z-A}\right|$


## Van der Pauw method

Conformal mappings Discrete integrable submanifolds

## Equipotential lines and current lines.

Conducting plane. Current flows in at $z=-1$ and flows out at $z=1$.


## Conducting half-plane.

Current $J$ flows in at $z=x_{1}$ and flows out at $z=x_{2}$, (where $x_{1}, x_{2}$ are real).
Conducting plane: real axis is a symmetry axis (and a current line).
Potential for conducting half-plane is the same as for the plane with the current $2 J$ (dividing equally into two half-planes).

$$
\Phi(z)=\frac{2 J \rho}{2 \pi d} \ln \left|\frac{z-x_{2}}{z-x_{1}}\right| .
$$


where $a=x_{2}-x_{1}, \quad b=x_{3}-x_{2}, c=x_{4}-x_{3}$.

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$$
\Phi(z)=\frac{2 J \rho}{2 \pi d} \ln \left|\frac{z-x_{2}}{z-x_{1}}\right|
$$

We compute: $R_{12,34}=\frac{\Phi\left(x_{4}\right)-\Phi\left(x_{3}\right)}{J_{12}}$. Hence (van der Pauw):

$$
R_{12,34}=\frac{\rho}{\pi d} \ln \left|\frac{x_{4}-x_{2}}{x_{4}-x_{1}} \cdot \frac{x_{3}-x_{1}}{x_{3}-x_{2}}\right| \equiv \frac{\rho}{\pi d} \ln \frac{(a+b)(b+c)}{b(a+b+c)}
$$

where $a=x_{2}-x_{1}, b=x_{3}-x_{2}, c=x_{4}-x_{3}$.

## Equipotential lines and current lines.

Conducting half-plane. Current flows in at $z=-1$ and flows out at $z=1$.


## Complex potential is holomorphic

Potencjał $\Phi(z)$ satisfies

$$
\Delta \Phi=\rho J \delta\left(z-x_{2}\right)-\rho J \delta\left(z-x_{1}\right),
$$

where $\delta$ is the Dirac delta. Therefore, we may define

$$
F(z)=\Phi(x, y)+i \Psi(x, y)
$$

where $\Psi$ is determined (up to a constant) from Cauchy-Riemann conditions:

$$
\frac{\partial \Phi}{\partial x}=\frac{\partial \Psi}{\partial y}, \quad \frac{\partial \Phi}{\partial y}=-\frac{\partial \Psi}{\partial x}
$$

$F$ is holomorphic outside sigular points $x_{1}, x_{2}$.

## Explicit form of the complex potential

 for the upper half-plane.$$
\Phi(z) \equiv \operatorname{Re} F(z)=\frac{J \rho}{\pi d} \ln \left|\frac{z-x_{2}}{z-x_{1}}\right|
$$

$$
\Psi(z)=\operatorname{Im} F(z)=\frac{J \rho}{\pi d}\left(\operatorname{Arg}\left(z-x_{2}\right)-\operatorname{Arg}\left(z-x_{1}\right)\right)
$$

## Boundary conditions:



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$$
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\end{gathered}
$$

Boundary conditions:

$$
\begin{gathered}
z \in\left(-\infty, x_{1}\right) \cup\left(x_{2}, \infty\right) \quad \Longrightarrow \quad \Psi(z)=0 \\
z \in\left(x_{1}, x_{2}\right) \quad \Longrightarrow \quad \Psi(z)=\frac{J \rho}{d}=\mathrm{const}
\end{gathered}
$$

## Riemann mapping theorem

Twierdzenie: Any simply connected region of the complex plane (except the whole complex plane) is conformally equivalent to the unit open disc.

Region: an open and connected subset of $\mathbb{C}$.
Conformal map: preserves angles.

## Conformal mappings of the complex plane:

 biholomorphic functions (i.e., the inverse function is also holomorphic).Any holomorphic function $w=f(z)$ (i.e., $u+i v=f(x+i y)$ ) such that $f^{\prime}(z) \neq 0$ is a conformal map.
(Counter)example: $f(z)=z^{2}$ is not conformal at $z=0$, because the angle between lines through $z=0$ is doubled after this transformation.
$N=2$ : conformal transformations are biholomorphic maps. Of special interest is a subgroup of Möbius transformations.

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## Disc and half-plane are conformally equivalent.

Function $w \mapsto z=i \frac{w+i}{i-w}$ is a biholomorphic map of the unit disc $(|w| \leqslant 1)$ onto the upper half-plane $(\operatorname{Im} z \geqslant 0)$.

The inverse function $\quad z \mapsto w=i \frac{z-i}{z+i}$.

| $w$ | 1 | $i$ | -1 | $-i$ |
| :---: | :---: | :---: | :---: | :---: |
| $z$ | 1 | $\infty$ | -1 | 0 |

All conformal maps of the upper half plane onto the unit disc:

$$
w=e^{i \theta} \frac{z-a}{z-\bar{a}}, \quad \operatorname{Im} a>0, \quad \theta \in \mathbb{R}
$$

## Christofell-Schwarz theorem:

Any polygon can be conformally mapped onto the upper half-plane.
Explicit formula for the map of the upper half-plane onto $n$-gon with angles: $k_{1} \pi, k_{2} \pi, \ldots, k_{n} \pi$ (where
$\left.k_{1}+k_{2}+\ldots+k_{n}=n-2\right)$ :

$$
\begin{gathered}
w(z)=A \int_{z_{0}}^{z}\left(\zeta-x_{1}\right)^{k_{1}-1} \ldots\left(\zeta-x_{n}\right)^{k_{n}-1} d \zeta+B \\
\frac{d w}{d z}=A\left(z-x_{1}\right)^{k_{1}-1} \ldots\left(z-x_{n}\right)^{k_{n}-1}
\end{gathered}
$$

Note that for $z=x \in\left(x_{j}, x_{j+1}\right)$ the phase of $\frac{d w}{d z}$ is constant! Therefore, indeed, this segment is mapped into a line segment: $w(x)=e^{i \theta} \int^{x}\left|w^{\prime}(x)\right| d x$.

## Conformal covariance of current lines and equipotential lines

A conformal (= biholomorphic) transformation: $\quad z \mapsto w=f(z)$.
$F(z)=\Phi+i \psi$ transforms as a scalar, i.e.,

$$
\tilde{F}(w)=F\left(f^{-1}(w)\right.
$$

thus $\tilde{F}$ is holomorphic, and $\tilde{\Phi}, \tilde{\Psi}$ satisfy a Poisson equation (Laplace equation outside singular points $w_{1}=f\left(x_{1}\right), w_{2}=f\left(x_{2}\right)$ ).
The same boundary conditions: $\Psi(z)=0, \Psi(z)=J \rho / d$.
Corollary: $\tilde{\Phi}, \tilde{\Psi}$ yield potential and current lines in the transformed region.

## The case non-simply connected is much more difficult.

 Typical counterexample: conformal mappings of an annulus.Annulus: $\quad\left\{z: r<\left|z-z_{0}\right|<R\right\} \quad$ has a single "hole".
Theorem: Two annuli, defined by $r_{1}, R_{1}$ and $r_{2}, R_{2}$,
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Corollary: Usually non-simply connected regions are not conformally equivalent.

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Van der Pauw's formula can be reformulated in terms of the cross ratio:

$$
R_{12,34}=\frac{\rho}{\pi d} \ln \left|\left(x_{1}, x_{2} ; x_{3}, x_{4}\right)\right|
$$

> Van der Pauw does not mention at all the cross ratio. His motivation
> came from electrodynamics (reciprocity theorem of passive multipoles). The same concerns other authors who developed or worked with the van der Pauw method.

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## Sign of the cross ratio

for points lying on the real axis, i.e., $z_{k} \equiv x_{k}$.
If segments $\left[x_{1}, x_{2}\right] i\left[x_{3}, x_{4}\right]$ partially overlap (have a common segment), then

$$
\left(x_{1}, x_{2} ; x_{3}, x_{4}\right)<0 .
$$

If these segments are disjoint or one is contained inside the other one, then

$$
\left(x_{1}, x_{2} ; x_{3}, x_{4}\right)>0 .
$$

If any of these segments degenerates to a point, then

$$
\left(x_{1}, x_{2} ; x_{3}, x_{4}\right)=1,
$$

which means that $\ln \left(x_{1}, x_{2} ; x_{3}, x_{4}\right)=0$.

## A new formula for the van der Pauw method

Following van der Pauw, we assume (to fix an attention):
$x_{1}<x_{2}<x_{3}<x_{4}$. Then:

$$
\left(x_{1}, x_{2} ; x_{3}, x_{4}\right)>0, \quad\left(x_{1}, x_{4} ; x_{3}, x_{2}\right)>0, \quad\left(x_{1}, x_{3} ; x_{2}, x_{4}\right)<0 .
$$

We recall:

$$
\left(x_{1}, x_{2} ; x_{3}, x_{4}\right)^{-1}+\left(x_{1}, x_{4} ; x_{3}, x_{2}\right)^{-1}=1, \quad \leftarrow \text { van der Pauw }
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& \left(x_{1}, x_{2} ; x_{3}, x_{4}\right)+\left(x_{1}, x_{3} ; x_{2}, x_{4}\right)=1 . \leftarrow \text { new formula? }
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& \left(x_{1}, x_{2} ; x_{3}, x_{4}\right)+\left(x_{1}, x_{3} ; x_{2}, x_{4}\right)=1 . \leftarrow \text { new formula? } \\
& \exp \left(-\frac{\pi d R_{12,34}}{\rho}\right)+\exp \left(-\frac{\pi d R_{14,32}}{\rho}\right)=1 \\
& \exp \frac{\pi d R_{12,34}}{\rho}-\exp \frac{\pi d R_{13,24}}{\rho}=1 \leftarrow \text { new formula! }
\end{aligned}
$$

## Was our "new identity" known to van der Pauw?

From identities: $\left(z_{1}, z_{2} ; z_{3}, z_{4}\right)^{-1}+\left(z_{1}, z_{4} ; z_{3}, z_{2}\right)^{-1}=1$, $\left(z_{1}, z_{2} ; z_{3}, z_{4}\right)+\left(z_{1}, z_{3} ; z_{2}, z_{4}\right)=1$, it follows

$$
\left(z_{1}, z_{3} ; z_{2}, z_{4}\right)=-\left(z_{1}, z_{2} ; z_{3}, z_{4}\right)\left(z_{1}, z_{4} ; z_{3}, z_{2}\right)^{-1}
$$

Rewriting it in terms of $R_{i j, k l}$

$$
\exp \frac{\pi d R_{13,24}}{\rho}=\exp \frac{\pi d R_{12,34}}{\rho} \exp \left(-\frac{\pi d R_{14,32}}{\rho}\right)
$$

we obtain an identity known to van der Pauw:

$$
R_{13,24}=R_{12,34}-R_{14,23} .
$$

## Some consequences of van der Pauw formulas (old and new)

$$
\begin{gathered}
\exp \left(-\frac{\pi d R_{12,34}}{\rho}\right)+\exp \left(-\frac{\pi d R_{14,32}}{\rho}\right)=1 \\
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$$

Corollary: $\quad R_{12,34}>0, \quad R_{14,32}>0, \quad R_{12,34}>R_{13,24}$
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we have: $\quad R_{13,24}>0$.

## Determining $\rho$ by the Banach fixed point method

 J.L.Cieśliński, preprint arXiv (2012).We use the new formula: $\exp \frac{\pi d R_{12,34}}{\rho}-\exp \frac{\pi d R_{13,24}}{\rho}=1$.


Banach fixed point theorem: $\quad \sigma=F(\sigma)$.

$0 \leqslant k<1$, therefore $\left|F^{\prime}(\sigma)\right|<1$, i.e., the iteration procedure is convergent (usually fast).

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\sigma=\frac{\ln \left(1+\exp \left(\pi d R_{13,24} \sigma\right)\right)}{\pi d R_{12,34}}, \quad \sigma=\frac{1}{\rho}
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F^{\prime}(\sigma)=\frac{k}{1+\exp \left(-\pi d R_{13,24} \sigma\right)}, \quad k=\frac{R_{13,24}}{R_{12,34}}
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## Conclusions

- Van der Pauw formula can be expressed by the cross ratio.
- We found a modification of the van der Pauw formula, solvable by the fast convergent fixed point iteration.
- A work on van der Pauw method for samples with a hole is in progress (Szymański-Cieśliński-Łapiński).


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## Discrete nets

Discrete nets: maps $F: \mathbb{Z}^{n} \rightarrow \mathbb{R}^{m}$.
The case $n=2$ : discrete surfaces immersed in $\mathbb{R}^{m}$.
The map $\mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$, obtained in the continuum limit from a discrete net, corresponds to a specific choice of coordinates on some smooth surface.

Notation. Forward and backward shift:

$$
\begin{aligned}
& T_{j} f\left(m^{1}, \ldots, m^{j}, \ldots, m^{n}\right)=f\left(m^{1}, \ldots, m^{j}+1, \ldots, m^{n}\right) \\
& T_{j}^{-1} f\left(m^{1}, \ldots, m^{j}, \ldots, m^{n}\right)=f\left(m^{1}, \ldots, m^{j}-1, \ldots, m^{n}\right)
\end{aligned}
$$

## Special classes of integrable discrete nets Bobenko-Pinkall, Doliwa-Santini, Cieślínski-Doliwa-Santini, Nieszporski, ..

Discrete asymptotic nets: any point $F$ and its all four neighbours ( $T_{1} F, T_{2} F, T_{1}^{-1} F, T_{2}^{-1} F$ ) are co-planar.
Discrete pseudospherical surfaces: asymptotic, Chebyshev (segments joining the neighbouring points have equal lengths).
Discrete conjugate nets: planar elementary quadrilaterals. Conjugate nets: the second fundamental form is diagonal.

Circular nets (every quadrilateral is inscribed into a circle) correspond to curvature lines (fundamental forms are diagonal).
Discrete isothemic nets: the cross-ratio for any elementary quadrilateral is a negative constant. Isothermic immersions: curvature lines admit conformal parameterization.

## Circular nets have scalar cross ratios

Elementary quadrilateral: four points $F, T_{k} F, T_{j} F, T_{k} T_{j} F$. Sides of the quadrilateral: $D_{k} F, D_{j} F, T_{k} D_{j} F, T_{j} D_{k} F$, where $D_{k} F:=T_{k} F-F$. We define $Q_{k j}(F):=Q\left(F, T_{k} F, T_{k j} F, T_{j} F\right)=\left(D_{k} F\right)\left(T_{k} D_{j} F\right)^{-1}\left(T_{j} D_{k} F\right)\left(D_{j} F\right)^{-1}$

Proposition. The net $F=F\left(m^{1}, \ldots, m^{n}\right)$ is a circular net if and only if $Q_{k j}(F) \in \mathbb{R}$ for any $k, j \in\{1, \ldots, n\}$.

## Circular nets by the Sym formula

We consider the Clifford algebra $\mathcal{C}(V \oplus W)$, where $\operatorname{dim} V=q, \operatorname{dim} W=r$. Let $\Psi$ satisfies:

$$
T_{j} \Psi=U_{j} \Psi, \quad(j=1, \ldots, n)
$$

where $n \leqslant q$, and $U_{j}=U_{j}\left(m^{1} \ldots, m^{n}, \lambda\right) \in \Gamma_{0}(V \oplus W)$ have the following Taylor expansion around a given $\lambda_{0}$ :

$$
\begin{aligned}
& U_{j}=\mathbf{e}_{j} B_{j}+\left(\lambda-\lambda_{0}\right) \mathbf{e}_{j} A_{j}+\left(\lambda-\lambda_{0}\right)^{2} C_{j} \ldots, \\
& A_{j} \in W, \quad B_{j} \in V, \quad \mathbf{e}_{j} \in V,
\end{aligned}
$$

$A_{j}, B_{j}$ are invertible, and $\mathbf{e}_{1}, \ldots, \mathbf{e}_{n}$ are orthogonal unit vectors.

## Circular nets by the Sym formula (continued)

Proposition. Discrete net $F$, defined by the Sym-Tafel formula

$$
F=\left.\Psi^{-1} \Psi_{, \lambda}\right|_{\lambda=\lambda_{0}},
$$

(where $\psi$ solves the above linear problem and mild technical assumptions that at least at a single point $m_{0}^{1}, \ldots, m_{0}^{n}$ we have: $\left.\Psi\left(m_{0}^{1}, \ldots, m_{0}^{n}, \lambda_{0}\right) \in \Gamma_{0}(V), \Psi\left(m_{0}^{1}, \ldots, m_{0}^{n}, \lambda\right) \in \Gamma_{0}(V \oplus W)\right)$,
can be identified with a circular net in $V \wedge W$ provided that

$$
A_{k}\left(T_{k} A_{j}\right)^{-1}\left(T_{j} A_{k}\right) A_{j}^{-1} \in \mathbb{R}
$$

Namely: $\left(F\left(m^{1}, \ldots, m^{n}\right)-F\left(m_{0}^{1}, \ldots, m_{0}^{n}\right)\right) \in V \wedge W$.

## Special projections generalizing Sym's approach.

Let $P: W \rightarrow \mathbb{R}$ is a projection $\left(P^{2}=P\right)$.
We extend its action on $V \wedge W$ (in order to get $P: V \wedge W \rightarrow V$ ) in a natural way. Namely, if $\mathbf{v}_{k} \in V$ and $\mathbf{w}_{k} \in W$, then

$$
P\left(\sum_{k} \mathbf{v}_{k} \mathbf{w}_{k}\right):=\sum_{k} P\left(\mathbf{w}_{k}\right) \mathbf{v}_{k} .
$$

Proposition. Let $P$ is a projection and $F$ is defined by the Sym-Tafel formula. Then $P(F)$ is a circular net.

## Discrete isothermic surfaces in $\mathbb{R}^{q}$

$$
\begin{aligned}
& U_{j}=\mathbf{e}_{j} B_{j}+\lambda \mathbf{e}_{j} A_{j} \quad(j=1,2), \\
& A_{j} \in W \simeq \mathbb{R}^{1,1}, \quad B_{j} \in V \simeq \mathbb{R}^{q}, \quad \mathbf{e}_{j} \in V \\
& \left(C_{j}=0, \quad \lambda_{0}=0\right), \\
& \text { projection: } \quad P\left(\mathbf{e}_{q+1}\right)=1, \quad P\left(\mathbf{e}_{q+2}\right)= \pm 1
\end{aligned}
$$

Smooth isothermic immersions admit isothermic (isometric) parameterization of curvature lines. In these coordinates $d s^{2}=\Lambda\left(d x^{2}+d y^{2}\right)$ and the second fundamental form is diagonal.

## Discrete Guichard nets in $\mathbb{R}^{q}$

Conjecture:

$$
\begin{aligned}
& U_{j}=\mathbf{e}_{j} B_{j}+\lambda \mathbf{e}_{j} A_{j}, \\
& A_{j} \in W \simeq \mathbb{R}^{2,1}, \quad B_{j} \in V \simeq \mathbb{R}^{q}, \quad \mathbf{e}_{j} \in V \\
& \left(C_{j}=0, \quad \lambda_{0}=0\right) \\
& P\left(\mathbf{e}_{q+1}\right)=\cos \varphi_{0}, P\left(\mathbf{e}_{q+2}\right)=\sin \varphi_{0}, P\left(\mathbf{e}_{q+3}\right)= \pm 1
\end{aligned}
$$

Guichard nets in $\mathbb{R}^{3}$ are characterized by the constraint $H_{1}^{2}+H_{2}^{2}=H_{3}^{2}$, where $H_{j}$ are Lamé coefficients, i.e., $d s^{2}=H_{1}^{2} d x^{2}+H_{2}^{2} d y^{2}+H_{3}^{2} d z^{2}$.

## Discretization of some class of orthogonal nets in $\mathbf{R}^{n}$

$$
\begin{aligned}
& U_{j}=\mathbf{e}_{j} B_{j}+\lambda \mathbf{e}_{j} A_{j}, \\
& A_{j} \in W \simeq \mathbb{R}^{n}, \quad B_{j} \in V \simeq \mathbb{R}^{n}, \quad \mathbf{e}_{j} \in V, \\
& \left(C_{j}=0, \quad \lambda_{0}=0\right), \\
& P\left(\mathbf{e}_{n+k}\right)=1, \quad P\left(\mathbf{e}_{n+j}\right)=0(j \neq k), \quad k \text { - fixed }
\end{aligned}
$$

This class in the smooth case is defined by the constraint $H_{1}^{2}+\ldots+H_{n}^{2}=$ const, where $d s^{2}=H_{1}^{2}\left(d x^{1}\right)^{2}+\ldots+H_{n}^{2}\left(d x^{n}\right)^{2}$.

## Discrete Lobachevsky $n$-spaces in $\mathbb{R}^{2 n-1}$

$$
\begin{aligned}
& U_{j}=\mathbf{e}_{j}\left(\frac{1}{2}\left(\lambda-\frac{1}{\lambda}\right) A_{j}+\frac{1}{2}\left(\lambda+\frac{1}{\lambda}\right) P_{j}+Q_{j}\right), \\
& V=V_{1} \oplus V_{2}, \quad V_{1} \simeq \mathbb{R}^{n}, \quad V_{2} \simeq \mathbb{R}^{n-1}, \quad W \simeq \mathbb{R}, \quad \lambda_{0}=1, \\
& \mathbf{e}_{j} \in V_{1}, \quad Q_{j} \in V_{1}, \quad P_{j} \in V_{2}, \quad A_{j} \in W, \quad P_{j}+Q_{j}=B_{j} .
\end{aligned}
$$

In the continuum limit we get immersions with the constant negative sectional curvature (Lobachevsky spaces).

## Conclusions and open problems

- Cliford cross ratio is a convenient tool to study circular nets (discrete analogue of curvature lines).
- Open problem: find purely geometric characterization of discrete nets generated by the Sym formula
- Open problem: Clifford cross ratio identities.
- Plans: Darboux-Bäcklund transformations and special solutions.
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## Thank you for attention!

## Original sources on the van der Pauw method

嗇 Leo J. van der Pauw,
A method of measuring specific resistivity and Hall effect of discs of arbitrary shape,
Philips Research Reports 13 (1958) 1-9.
Reo J. van der Pauw,
A method of measuring the resistivity and Hall coefficient on lamellae of arbitrary shape, Philips Technical Review 20 (1958) 220-224.

Both papers available through Wikipedia. Moreover, perpaps:
Q L.V. Bewley.
Two-dimensional fields in electrical engineering.
MacMillan, New York 1948.

## Generalization of the Riemann mapping theorem. Uniformization theorem [Riemann-Poincaré-Koebe]

Uniformization theorem extends the Riemann mapping theorem on Riemann surfaces:

Any simply connected Riemann surface is conformally equivalent (biholomorphically isomorphic) to

- unit disc $|z|<1$
- complex plane $\mathbb{C}$
- Riemann sphere $\mathbb{C} P(1)$

