

GRADIENT AND DIVERGENCE ON SYMPLECTIC MANIFOLDS

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Let (M, ω) be a symplectic manifold of dimension $2n$ and let x be a point of this manifold. Denote by $T_x M$ and $T_x^* M$ the tangent space and the cotangent space at x , respectively.

The symplectic form can be transmitted to the bilinear form acting on covectors, in the following way

$$\omega(\eta, \xi) = \omega(\eta^\sharp, \xi^\sharp),$$

where $\eta, \xi \in T_x^* M$ and for any one form η , η^\sharp is defined by

$$\eta(v) = \omega(\eta^\sharp, v), \quad v \in T_x M.$$

This form induces bilinear pairings on each $\Lambda^p T_x^* M$, $p = 1, \dots, 2n$, also denoted by ω and defined by

$$\omega(\eta_1 \wedge \dots \wedge \eta_p, \xi_1 \wedge \dots \wedge \xi_p) = \det(\omega(\eta_i, \xi_j)_{i,j=1,\dots,p}),$$

where $\eta_i, \xi_j \in T_x^* M$ for any $i, j = 1, \dots, p$.

Consider two spaces:

$\Lambda^p = C^\infty(\Lambda^p T^*M)$ - the space of scalar-valued p-forms,

$\vec{\Lambda}^p = C^\infty(\Lambda^p T^*M \otimes TM)$ - the space of vector-valued p-forms.

Now, the symplectic form can be extended to the space of vector-valued forms by the formula

$$\omega(\varphi \otimes X, \psi \otimes Y) = \omega(\varphi, \psi)\omega(X, Y),$$

for any $\varphi \otimes X, \psi \otimes Y \in \vec{\Lambda}^p$. Additionally,

- (i) $\omega(\varphi \otimes X, Y) = \omega(X, Y) \cdot \varphi$, for any $\varphi \otimes X \in \vec{\Lambda}^p$ and $Y \in \Gamma(TM)$,
- (ii) $\omega(\eta \otimes \varphi, \xi \otimes \psi) = \omega(\eta, \xi) \cdot \omega(\varphi, \psi)$, for any $\eta \otimes \varphi, \xi \otimes \psi \in C^\infty(T^*M \otimes \Lambda^p T^*M)$.

Define three exterior products (all denoted by the same symbol):

$$\wedge : \Lambda^p \times \Lambda^q \rightarrow \Lambda^{p+q} \quad \varphi \wedge \psi;$$

$$\wedge : \Lambda^p \times \vec{\Lambda}^q \rightarrow \vec{\Lambda}^{p+q} \quad \varphi \wedge (\psi \otimes X) = (\varphi \wedge \psi) \otimes X;$$

$$\wedge : \vec{\Lambda}^p \times \vec{\Lambda}^q \rightarrow \Lambda^{p+q} \quad (\varphi \otimes X) \wedge (\psi \otimes Y) = (\varphi \wedge \psi) \cdot \omega(X, Y).$$

Definition 1

A symplectic covariant derivative on (M, ω) is a smooth linear covariant derivative ∇ such that:

$$T^\nabla = 0, \quad \nabla\omega = 0.$$

Take ∇ any symplectic covariant derivative. This operator can be extended to the tensor algebra and the next to the space of vector-valued p-forms for any vector field Y according to the formula

$$\nabla_Y : \vec{\Lambda}^p \ni \varphi \otimes X \mapsto \nabla_Y \varphi \otimes X + \varphi \otimes \nabla_Y X \in \vec{\Lambda}^p.$$

Differential operators on symplectic manifolds

Let $d : \Lambda^p \rightarrow \Lambda^{p+1}$ be the operator of exterior derivation. It can be extended to the space of vector-valued forms according to the formula

$$d : \vec{\Lambda}^p \ni \varphi \otimes X \mapsto d\varphi \otimes X + (-1)^p \varphi \wedge \nabla X \in \vec{\Lambda}^{p+1}.$$

Proposition 1

- (1) For any $\varphi \in \Lambda^p$ and $\psi \in \Lambda^q$, $d(\varphi \wedge \psi) = d\varphi \wedge \psi + (-1)^p \varphi \wedge d\psi$.
- (2) For any $\varphi \in \Lambda^p$ and $\Psi \in \vec{\Lambda}^q$, $d(\varphi \wedge \Psi) = d\varphi \wedge \Psi + (-1)^p \varphi \wedge d\Psi$.
- (3) For any $\Phi \in \vec{\Lambda}^p$ and $\Psi \in \vec{\Lambda}^q$, $d(\Phi \wedge \Psi) = d\Phi \wedge \Psi + (-1)^p \Phi \wedge d\Psi$.

Differential operators on symplectic manifolds

Let e_1, \dots, e_{2n} be a local symplectic base on M and let e^1, \dots, e^{2n} be a dual base to e_1, \dots, e_{2n} . Note, that M is oriented, so

$$\Omega = \frac{1}{n!} \omega^n = (-1)^{\frac{n(n-1)}{2}} e^1 \wedge e^2 \wedge \dots \wedge e^{2n}.$$

Definition 2

The linear operator $*$: $\Lambda^p \rightarrow \Lambda^{2n-p}$ defined by

$$\varphi \wedge * \psi = \omega(\varphi, \psi) \Omega, \quad \text{for all } \varphi, \psi \in \Lambda^p$$

is called the symplectic Hodge star operator.

The symplectic Hodge star operator can be extended to the space of vector-valued forms according to the formula

$$* : \vec{\Lambda}^p \ni \varphi \otimes X \mapsto (*\varphi) \otimes X \in \vec{\Lambda}^{2n-p}.$$

Definition 3

The linear operator $tr : \Lambda^p \rightarrow \Lambda^{p-2}$ defined by

$$tr\varphi = \sum_{k=1}^n \iota_{e_{n+k}} \iota_{e_k} \varphi \quad \text{for all } \varphi \in \Lambda^p$$

is called the symplectic trace operator, where e_1, \dots, e_{2n} is the local symplectic base on M .

Moreover, we also define the symplectic trace operator acting on the space of vector-valued forms:

$$Tr : \vec{\Lambda}^p \ni \varphi \otimes X \longmapsto \iota_X \varphi \in \Lambda^{p-1}.$$

Gradient and divergence in the Rummel sense

Definition 4

Define the linear operator $j : \Lambda^p \rightarrow \vec{\Lambda}^{p-1}$ by the formula

$$\omega(j\varphi, X) = \iota_X \varphi,$$

for any $\varphi \in \Lambda^p, X \in \Gamma(TM)$.

Proposition 2

Let e_1, \dots, e_{2n} be a local symplectic base of M on a neighborhood U .

For any $\varphi \in \Lambda^p$, we have

$$j\varphi = \sum_{k=1}^n \iota_{e_{n+k}} \varphi \otimes e_k - \iota_{e_k} \varphi \otimes e_{n+k} \text{ in } U.$$

Proposition 3

For any $\varphi \in \Lambda^p$ and $\psi \in \Lambda^q$, $j(\varphi \wedge \psi) = j\varphi \wedge \psi + (-1)^p \varphi \wedge j\psi$.

Definition 5

Define the linear operator $\alpha : \vec{\Lambda}^p \rightarrow \Lambda^{p+1}$ by the formula

$$\alpha(\varphi \otimes X) = X^b \wedge \varphi,$$

for any $\varphi \otimes X \in \vec{\Lambda}^p$, where one form X^b is defined by

$$X^b(Y) = \omega(X, Y), \text{ for any vector field } Y.$$

Proposition 4

For any $\varphi \in \Lambda^p$ and $\Psi \in \vec{\Lambda}^p$, we have $\omega(j\varphi, \Psi) = \omega(\varphi, \alpha\Psi)$.

Moreover, we have

Proposition 5

For any $\varphi \in \Lambda^p$, $\alpha j\varphi = p\varphi$.

The definitions of symplectic trace operators imply the following

Proposition 6

For any $\varphi \in \Lambda^p$,

$$\text{Tr}_j \varphi = -2 \text{tr} \varphi.$$

Moreover, the symplectic trace operator acting on vector exterior forms satisfies

Proposition 7

For any $\Phi \in \vec{\Lambda}^p$,

$$\text{Tr} \Phi = (-1)^p * \alpha * \Phi.$$

Now, two first order linear operators grad and div will be introduced. The first one acts on scalar exterior forms.

Definition 6

The differential operator $\text{grad} : \Lambda^p \rightarrow \vec{\Lambda}^p$ defined by

$$\text{grad} = jd + dj$$

is called the gradient.

Remark 1

For any $f \in \Lambda^0$ and $X \in \vec{\Lambda}^0$, $\omega(\text{grad}f, X) = X(f)$.

Gradient and divergence in the Rummier sense

Definition 7

The differential operator $\operatorname{div} : \vec{\Lambda}^p \rightarrow \Lambda^p$ defined by

$$\operatorname{div} = \operatorname{Tr}d + d\operatorname{Tr}$$

is called the divergence.

Proposition 8

For any $\Phi \in \vec{\Lambda}^p$, we have

$$\operatorname{div}(\Phi) = \operatorname{Tr} \nabla(\Phi).$$

In particular, $\operatorname{div}(X) = \operatorname{Tr}(\nabla X)$.

Proposition 9

For any $\varphi \otimes X \in \vec{\Lambda}^p$, we have $\operatorname{div}(\varphi \otimes X) = \nabla_X \varphi + \varphi \cdot \operatorname{div}(X)$.

Theorem 1

(1) For any $\varphi \in \Lambda^p$ and $\psi \in \Lambda^q$,

$$\mathbf{grad}(\varphi \wedge \psi) = \mathbf{grad}\varphi \wedge \psi + \varphi \wedge \mathbf{grad}\psi.$$

(2) For any $\varphi \in \Lambda^p$ and $\Psi \in \vec{\Lambda}^q$,

$$\mathbf{div}(\varphi \wedge \Psi) = \mathbf{grad}\varphi \wedge \Psi + \varphi \wedge \mathbf{div}\Psi.$$

(3) For any $\varphi \in \Lambda^p$ and $\Psi \in \vec{\Lambda}^q$,

$$\mathbf{Tr}(\varphi \wedge \Psi) = j\varphi \wedge \Psi + (-1)^p \varphi \wedge \mathbf{Tr}\Psi.$$

Gradient and divergence in the Rummier sense

Theorem 2

Let e_1, \dots, e_{2n} be a local symplectic base of M on a neighborhood U . Let e^1, \dots, e^{2n} be its dual base. For any $\varphi \in \Lambda^p$, we have

$$\mathit{grad} \varphi = \sum_{k=1}^n \nabla_{e_{n+k}} \varphi \otimes e_k - \nabla_{e_k} \varphi \otimes e_{n+k} \text{ in } U.$$

Proposition 10

For any vector field X and for any $\varphi \in \Lambda^p$, we have

$$\mathit{grad} \varphi \wedge X = \nabla_X \varphi.$$

Proposition 11

- (1) For any $f \in \Lambda^0$, $\mathit{grad} df = d \mathit{grad} f$.
- (2) For any $\varphi \in \Lambda^p$, $\mathit{grad} d\varphi = d \mathit{grad} \varphi + d^2 j\varphi$.

It holds the following relations:

Theorem 3

For any vector field X ,

$$(1) \quad j\nabla_X = \nabla_X j.$$

$$(2) \quad *\nabla_X = \nabla_X*.$$

Theorem 4

$$(1) \quad *grad = grad*;$$

$$(2) \quad *div = div*.$$

Formally adjoint operators

For any $\theta \in \Lambda^p$ and $\vartheta \in \Lambda^p$, we define the global product θ and ϑ by

$$(\theta, \vartheta) = \int_M \theta \wedge * \vartheta,$$

or equivalently

$$(\theta, \vartheta) = \int_M \omega(\theta, \vartheta) \cdot \Omega,$$

if the integral on the right-hand side exists.

It is defined by analogy for vector exterior forms.

Definition 8

The operator L is called formally adjoint to L^\dagger , if the following condition is satisfied

$$(L\theta, \vartheta) = (\theta, L^\dagger \vartheta),$$

if only θ or ϑ has the compact support.

Definition 9

Define the differential operator $\delta : \Lambda^p \rightarrow \Lambda^{p-1}$ by

$$\delta\varphi = (-1)^p(*d*)\varphi, \text{ for all } \varphi \in \Lambda^p.$$

Between, the operators grad , α and classical operators $*$, d and δ , there hold the following relations:

Proposition 12

(1) $d = \alpha \text{ grad}$.

(2) $\delta = \text{Tr grad}$.

Formally adjoint operators

It turns out, that the following operators are formally adjoint:

Theorem 5

δ is formally adjoint to d , i.e.

$$(d\varphi, \psi) = (\varphi, \delta\psi),$$

for any $\varphi \in \Lambda^{p-1}$ and $\psi \in \Lambda^p$, if only φ or ψ has a compact support.

Theorem 6

$-\text{div}$ is formally adjoint to grad , i.e.

$$(\text{grad}\varphi, \Psi) = (\varphi, -\text{div}\Psi),$$

for any $\varphi \in \Lambda^p$ and $\Psi \in \vec{\Lambda}^p$, if only φ or Ψ has a compact support.

Definition 10

Define the differential operator $\nabla^* : C^\infty(T^*M \otimes \Lambda^p T^*M) \rightarrow \Lambda^p$ by

$$\begin{aligned} (\diamond) \quad \nabla^*(\Xi) &= \sum_{k=1}^n \nabla_{e_{n+k}} \lrcorner_{e_k} \Xi - \nabla_{e_k} \lrcorner_{e_{n+k}} \Xi \\ &\quad - \operatorname{div}(e_k) \cdot \lrcorner_{e_{n+k}} \Xi + \operatorname{div}(e_{n+k}) \cdot \lrcorner_{e_k} \Xi, \end{aligned}$$

for any $\Xi \in C^\infty(T^*M \otimes \Lambda^p T^*M)$ and for any local symplectic base e_1, \dots, e_{2n} on M .

Proposition 13

For any $\xi \otimes \varphi \in C^\infty(T^*M \otimes \Lambda^p T^*M)$,

$$\nabla^*(\xi \otimes \varphi) = -\nabla_{\xi^\#} \varphi - \varphi \cdot \operatorname{div} \xi^\#.$$

Proposition 14

For any covariant derivative on M such, that $\nabla\omega = 0$ (not necessarily $T = 0$) and for any compactly supported vector field X on M

$$\int_M (\operatorname{div} X + \omega(X, \tau)) \Omega = 0,$$

where for any local symplectic base e_1, \dots, e_{2n} on M ,

$$\tau = \sum_{k=1}^n T(e_k, e_{n+k}).$$




With respect to the global products,

Theorem 7

∇^* is formally adjoint to ∇ i.e.

$$(\nabla\varphi, \Xi) = (\varphi, \nabla^*\Xi),$$

for any $\varphi \in \Lambda^p$ and $\Xi \in C^\infty(T^*M \otimes \Lambda^p T^*M)$, if only φ or Ξ has a compact support.

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